

General Description

The MAX13450E/MAX13451E are half-duplex and full-

duplex RS-485/RS-422 transceivers. These devices fea-

ture internal 100Ω and 120Ω termination resistors. The

resistor values are pin selectable. A logic supply input

The MAX13450E/MAX13451E feature strong drivers

specified to drive low-impedance lines found when a fully loaded bus, based on today's 100Ω characteristic

impedance cable, is doubly terminated. Both devices

allow slew-rate limiting of the driver output to reduce EMI

The MAX13451E has a FAULT alarm indication output to

signal to the system that an error condition exists in the driver. The MAX13451E also features a logic inversion

function. The logic inversion allows phase reversal of the

A-B signals in case these are inadvertently connected

The MAX13450E/MAX13451E have 1/8-unit load receiver

input impedance, allowing up to 256 transceivers on the

bus. All driver outputs are protected to ±30kV ESD using

The MAX13450E/MAX13451E are available in a 14-pin

TSSOP package and operate over the automotive -40°C

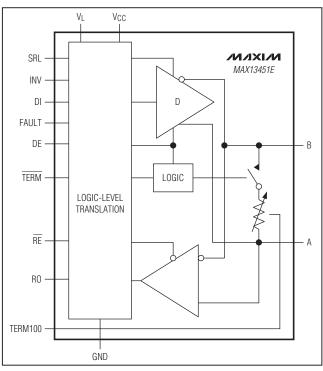
allows interfacing to logic levels down to +1.8V.

and reflections for data rates up to 500kbps.

_Features

- 100Ω/120Ω Pin-Selectable Internal Termination Resistors
- Driver Drives 100Ω Double Termination
- + 20Mbps (max) Data Rate
- Pin-Selectable Slew-Rate Limiting
- Logic Supply Input Allows Interfacing Down to 1.8V
- Driver Fault-Indication Output (MAX13451E)
- Inverting of A, B Line Polarity (MAX13451E)
- High-Impedance Driver Output/Receiver Input When V_{CC} Supply is Removed
- + Hot-Swap Input Structure on DE, RE, and TERM
- Extended ESD Protection ±30kV Human Body Model ±15kV Air Gap Discharge per IEC 61000-4-2 ±7kV Contact Discharge per IEC 61000-4-2
- 1/8-Unit Load Allows Up to 256 Transceivers on the Bus
- Thermal and Overcurrent Protected
- ♦ Fail-Safe Receivers
- +4.5V to +5.5V Supply Voltage Range

Functional Diagram (MAX13451E)



Applications Industrial Control Systems

- Portable Industrial Equipment
- Motor Control

wrongly.

Security Networks

the Human Body Model (HBM).

to +125°C temperature range.

Medical Networks

_Ordering Information/ Selector Guide

PART	HALF/FULL DUPLEX	PIN-PACKAGE	
MAX13450EAUD+	Full	14 TSSOP-EP*	
MAX13451EAUD+	Half	14 TSSOP-EP*	

Note: All devices are specified over the -40°C to +125°C operating temperature range.

+Denotes a lead(Pb)-free/RoHS-compliant package. *EP = Exposed pad.

Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

(All voltages referenced to GND.)

(/	
DE, RE, DI, RO,	TERM, TERM100, SRL	0.3V to (VL + 0.3V)
INV, FAULT		0.3V to (VL + 0.3V)
A, B, Z, Y		8V to +13V
A to B (High-Z S	State)	+14V
B to A (High-Z S	State)	+14V
Short-Circuit Du	ration (RO, Y, Z) to GND .	Continuous

Continuous Power Dissipation (TA = $+70^{\circ}$ C)

TSSOP (derate 25.6mW/°C above +70°C)	2051mW
Operating Temperature Range	40°C to +125°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

PACKAGE THERMAL CHARACTERISTICS (Note 1)

TSSOP

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a fourlayer board. For detailed information on package thermal considerations, refer to <u>www.maxim-ic.com/thermal-tutorial</u>.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(V_{CC} = +4.5V to +5.5V, V_L = +1.62V to V_{CC}, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at V_{CC} = +5V, V_L = +1.8V, and T_A = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Supply Voltage	Vcc		4.5		5.5	V	
Logic Supply Voltage	VL		1.62	1.8	Vcc	V	
Supply Current	Icc	$DE = \overline{RE} = high, \overline{TERM} = high, no load$			6	mA	
Supply Current	ICC	$DE = \overline{RE} = low, \overline{TERM} = low, no load$			12	mA	
Logic Supply Current	IL	Current into V _L , no load on RO, device not switching, DE = \overline{RE} = high			2	μA	
Shutdown Current		Current into V _{CC} , DE = low, $\overline{RE} = \overline{TERM} =$ high			30	μA	
Shutdown Current	ISHDN	Current into V _{CC} , DE = low, \overline{RE} = high, TERM = low			8	mA	
DRIVER							
Differential Driver Output	Vod	$R_{DIFF} = 100\Omega$, Figure 1 (Note 3)	2.0		Vcc	V	
Differential Driver Output	VOD	$R_{DIFF} = 46\Omega$, Figure 1 (Note 3)	1.5		Vcc	v	
Change in Magnitude of Differential Output Voltage	ΔVod	RDIFF = 100Ω or 46Ω , Figure 1 (Note 3)			0.2	V	
Driver Common-Mode Output Voltage	Voc	RDIFF = 100Ω or 46Ω , Figure 1 (Note 3)		Vcc/2	3	V	
Change In Magnitude of Common-Mode Voltage	ΔV _{OC}	$R_{DIFF} = 100\Omega \text{ or } 46\Omega, \text{ Figure 1 (Note 3)}$			0.2	V	
Driver Short-Circuit Output	loop	$0V \le V_{OUT} \le +12V$			+280	mA	
Current	IOSD	$-7V \le V_{OUT} \le 0V$	-250				

ELECTRICAL CHARACTERISTICS (continued)

(V_{CC} = +4.5V to +5.5V, V_L = +1.62V to V_{CC}, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at V_{CC} = +5V, V_L = +1.8V, and T_A = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIO	NS	MIN	TYP	MAX	UNITS
Driver Short-Circuit Foldback		$(V_{CC} - 1V) \le V_{OUT} \le +12V$	/	+15			mΛ
Output Current	IOSDF	$-7V \le V_{OUT} \le 0V$				-15	mA
RECEIVER							
		$DE = \overline{RE} = GND;$	$V_A \text{ or } V_B = +12V$			125	
Input Current (A and B)	IA, B	$\overline{\text{TERM}} = V_{L}; V_{CC} = \text{GND}$ or 5.5V	$V_A \text{ or } V_B = -7V$	-100			μA
Receiver Differential Threshold Voltage	VTH	$\label{eq:constraint} \begin{array}{l} -7V \leq V_{CM} \leq +12V, \\ DE = \overline{RE} = GND; \\ \overline{TERM} = V_L; \ V_{CC} = GND \end{array}$	$V_A \text{ or } V_B = +12V$	-200		-50	mV
Receiver Input Hysteresis	ΔVth	VA + VB = 0V			15		mV
LOGIC INTERFACE							
Input High Voltage	Vih	DI, DE, RE, TERM, SRL, T	ERM100, INV	2/3 x VL			V
Input Low Voltage	VIL	DI, DE, RE, TERM, SRL, T	ERM100, INV			$1/3 \times V_L$	V
Input Current	lin	DI, DE, RE, TERM, TERM	100, SRL, INV	-1		+1	μA
Receiver Output High Voltage	VROH	Iout = -1mA		VL - 0.6			V
Receiver Output Low Voltage	VROL	$I_{OUT} = +1mA$				0.4	V
Three-State Output Current at Receiver	IOZR	$0V \le V_{RO} \le V_L$		-1	+0.01	+1	μA
Receiver Output Short-Circuit Current	IOSR	$0V \le V_{RO} \le V_L$		±1		±80	mA
Fault Output High Voltage (MAX13451E)	VFAULTH	Fault condition, IOUT = -1	Fault condition, IOUT = -1mA				V
Fault Output Low Voltage (MAX13451E)	VFAULTL	Nonfault condition; IOUT =	= +1mA			0.4	V
TERMINATION RESISTOR							
100 Ω Termination Resistor	R ₁₀₀	TERM = low, TERM100 =	high	85	100	115	Ω
120 Ω Termination Resistor	R120	TERM = low, TERM100 =	low	101	120	139	Ω
Single-Ended Input Capacitance vs. GND	CIN	f = 1MHz (MAX13451E only)			40		pF
ESD PROTECTION							
		Human Body Model			±30		
ESD Protection (A, B, Y, Z)		IEC 61000-4-2 Air Gap Di	scharge	±15			kV
		IEC 61000-4-2 Contact Di	scharge		±7		
ESD Protection (All Other Pins)		Human Body Model			±2		

SWITCHING CHARACTERISTICS—SRL = HIGH

(V_{CC} = +4.5V to +5.5V, V_L = +1.62V to V_{CC}, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at V_{CC} = +5V, V_L = +1.8V and T_A = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
DRIVER							
Driver Dreperation Daley	t DPLH				800		
Driver Propagation Delay	tDPHL	RDIFF = 54Ω , CL = 50pF, Figures 2 and 3			800	- ns	
Differential Driver Output Skew ItDPLH - tDPHLI	t DSKEW	W RDIFF = 54Ω , CL = 50pF, Figure 3			100	ns	
Driver Differential Output Rise or	tHL				600		
Fall Time	tLH	RDIFF = 54Ω , CL = 50pF, Figures 2 and 3	100		600	ns	
Maximum Data Rate	DRMAX		500			kbps	
Driver Enable from Shutdown to Output High	tDZH(SHDN)	S2 closed, RL = 500 Ω , CL = 100pF, Figures 4 and 5			4500	ns	
Driver Enable from Shutdown to Output Low	tDZL(SHDN)	S1 closed, R _L = 500 Ω , C _L = 100pF, Figures 4 and 5			5200	ns	
Driver Disable Delay	t _{DLZ} , t _{DHZ}	Figures 4 and 5			100	ns	
Driver Enable Delay	tdzl, tdzh	Figures 4 and 5			2500	ns	
RECEIVER							
Receiver Propagation Delay	trplh	$C_L = 15 pF$, $ V_{ID} \ge 2.0V$; t_{LH} , $t_{HL} \le 15 ns$,			200	ns	
neceiver Fropagation Delay	t _{RPHL}	Figures 6 and 7			200	115	
Receiver Output Skew	t RSKEW	$C_L = 15 pF$, Figures 6 and 7			30	ns	
Maximum Data Rate	DRMAX		500			kbps	
Receiver Enable to Output High	^t RZH	S2 closed, CL = 100pF, RL = 500 Ω , Figures 8 and 9			50	ns	
Receiver Enable to Output Low	trzl	S1 closed, CL = 100pF, RL = 500 Ω , Figures 8 and 9			50	ns	
Receiver Disable from High	tRHZ	Figures 8 and 9			50	ns	
Receiver Disable from Low	tRLZ	Figures 8 and 9			50	ns	
Receiver Enable from Shutdown to Output High	tRZH(SHDN)	Figures 8 and 9			5000	ns	
Receiver Enable from Shutdown to Output Low	trzl(SHDN)	Figures 8 and 9			5000	ns	
TERMINATION RESISTOR		·				~	
Turn-Off Time	trtz	Figure 10		120		μs	
Turn-On Time	t RTEN	Figure 10		1		μs	

SWITCHING CHARACTERISTICS—SRL = LOW

(VCC = +4.5V to +5.5V, VL = +1.62V to VCC, TA = TMIN to TMAX, unless otherwise noted. Typical values are at VCC = +5V, VL = +1.8V, and TA = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
DRIVER							
Driver Preservice Delay	t DPLH				50		
Driver Propagation Delay	t DPHL	RDIFF = 54Ω , CL = 50pF, Figures 2 and 3			50	- ns	
Differential Driver Output Skew ItDPLH - tDPHLI	t DSKEW	RDIFF = 54 Ω , CL = 50pF, Figure 3			6	ns	
Driver Differential Output Rise or Fall Time	thl, tlh	RDIFF = 54Ω , CL = 50pF, Figures 2 and 3			15	ns	
Maximum Data Rate	DRMAX		20			Mbps	
Driver Enable from Shutdown to Output High	tDZH(SHDN)	S2 closed, RL = 500 Ω , CL = 100pF, Figures 4 and 5			2000	ns	
Driver Enable from Shutdown to Output Low	tDZL(SHDN)	S1 closed, R _L = 500 Ω , C _L = 100pF, Figures 4 and 5			2000	ns	
Driver Disable Delay	t _{DLZ} , t _{DHZ}	Figures 4 and 5			100	ns	
Driver Enable Delay	tdzl, tdzh	Figures 4 and 5			100	ns	
RECEIVER							
Receiver Propagation Delay	tRPLH	$C_L = 15 pF$, $ V_{ID} \ge 2.0V$; t_{LH} , $t_{HL} \le 15 ns$,			50		
neceiver Fropagation Delay	t RPHL	Figures 6 and 7			50	ns	
Receiver Output Skew	t RSKEW	CL = 15pF, Figures 6 and 7			6	ns	
Maximum Data Rate	DRMAX		20			Mbps	
Receiver Enable to Output High	trzh	S2 closed, CL = 100pF, RL = 500 Ω , Figures 8 and 9			50	ns	
Receiver Enable to Output Low	t _{RZL}	S1 closed, CL = 100pF, RL = 500 Ω , Figures 8 and 9			50	ns	
Receiver Disable Time from High	t _{RHZ}	Figures 8 and 9			50	ns	
Receiver Disable Time from Low	t _{RLZ}	Figures 8 and 9			50	ns	
Receiver Enable from Shutdown to Output High	trzh(SHDN)	Figures 8 and 9			2000	ns	
Receiver Enable from Shutdown to Output Low	trzl(SHDN)	Figures 8 and 9			2000	ns	
TERMINATION RESISTOR		·					
Turn-Off Time	trtz	Figure 10		120		μs	
Turn-On Time	t RTEN	Figure 10		1		μs	

Note 2: All devices are 100% production tested at $T_A = +25^{\circ}C$. Limits over temperature are guaranteed by design. **Note 3:** Termination resistance is disabled (TERM = high).

 $(V_{CC} = +5V, V_L = +1.8V, T_A = +25^{\circ}C, unless otherwise noted.)$ SUPPLY CURRENT SHUTDOWN CURRENT **RECEIVER OUTPUT VOLTAGE** vs. DATA RATE vs. TEMPERATURE vs. OUTPUT CURRENT 70 10 5 9 SOURCE 60 RECEIVER OUTPUT VOLTAGE (V) 8 4 $R_{I} = 54\Omega$ SHUTDOWN CURRENT (µA) SUPPLY CURRENT (mA) 50 7 $R_{I} = 100\Omega$ 6 3 40 5 30 2 4 3 20 2 1 10 SINK 1 NO LOAD 0 0 0 0.1 10 -40 -25 -10 5 20 35 50 65 80 95 110 125 10 100 0 20 30 40 50 60 70 1 DATA RATE (Mbps) TEMPERATURE (°C) OUTPUT CURRENT (mA) **RECEIVER OUTPUT HIGH VOLTAGE RECEIVER OUTPUT LOW VOLTAGE RECEIVER PROPAGATION DELAY** vs. TEMPERATURE vs. TEMPERATURE vs. TEMPERATURE 2.0 0.5 100 $I_{OUT} = 1 mA$ I_{OUT} = 1mA INV = HIGH RECEIVER OUTPUT LOW VOLTAGE (V) RECEIVER OUTPUT HIGH VOLTAGE (V) RECEIVER PROPAGATION DELAY (ns) 1.8 0.4 80 1.6 0.3 60 INV = LOW 0.2 40 1.4 1.2 0.1 20 1.0 0 0 -40 -25 -10 5 20 35 50 65 80 95 110 125 -40 -25 -10 5 20 35 50 65 80 95 110 125 -40 -25 -10 5 20 35 50 65 80 95 110 125 TEMPERATURE (°C) TEMPERATURE (°C) TEMPERATURE (°C) TRANSMITTER OUTPUT CURRENT TRANSMITTER OUTPUT CURRENT **DRIVER DIFFERENTIAL OUTPUT CURRENT** vs. TRANSMITTER OUTPUT HIGH VOLTAGE TRANSMITTER OUTPUT LOW VOLTAGE vs. DIFFERENTIAL OUTPUT VOLTAGE 2V 120 200 100 DRIVER DIFFERENTIAL OUTPUT CURRENT (mA) 180 **FRANSMITTER OUTPUT CURRENT (mA) FRANSMITTER OUTPUT CURRENT (mA)** 100 160 80 140 80 120 60 60 100 80 40 40 60 40 20 20 20 0 0 0 2 -7 -2 3 -3 2 12 ٥ 3 4 5 7 1 TRANSMITTER OUTPUT LOW VOLTAGE (V) TRANSMITTER OUTPUT HIGH VOLTAGE (V) DRIVER DIFFERENTIAL OUTPUT VOLTAGE (V)

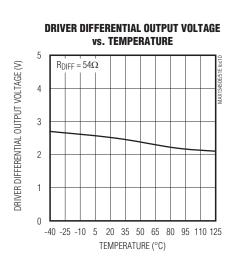
Typical Operating Characteristics

MAX13450E/MAX13451E

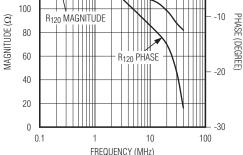


Typical Operating Characteristics (continued)

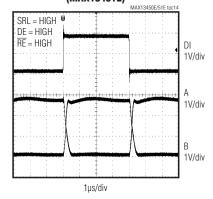
 $(V_{CC} = +5V, V_{L} = +1.8V, T_{A} = +25^{\circ}C, unless otherwise noted.)$

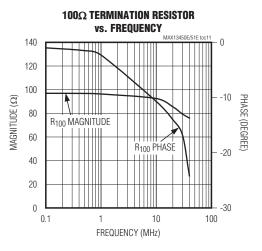




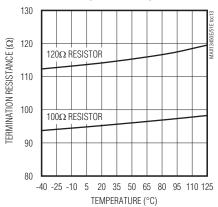




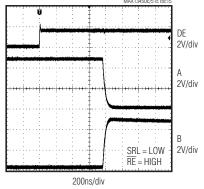


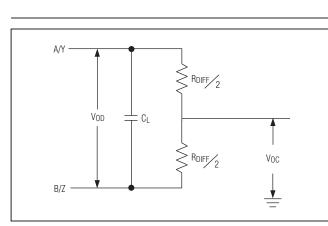


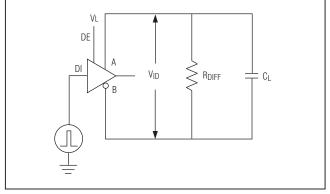
TERMINATION RESISTANCE vs. TEMPERATURE







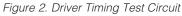




Test Circuits and Waveforms

Figure 1. Driver DC Test Load

MAX13450E/MAX13451E



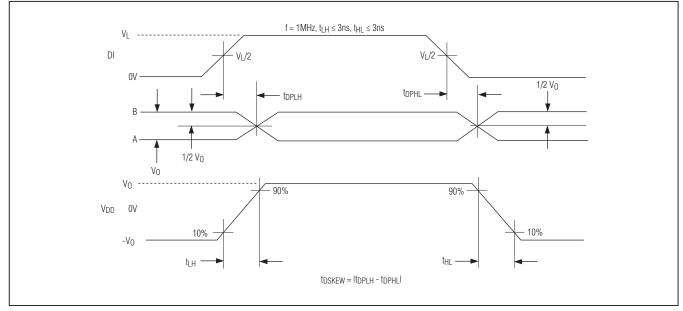


Figure 3. Driver Propagation Delays

_Test Circuits and Waveforms (continued)

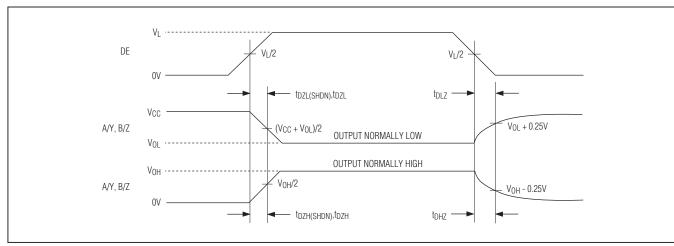
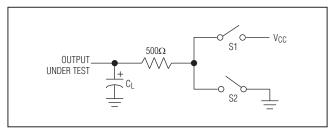


Figure 4. Driver Enable and Disable Times



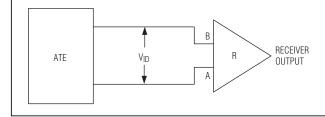
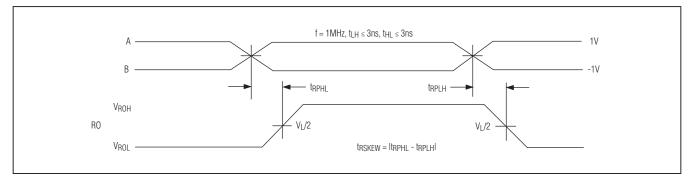


Figure 5. Driver-Enable and Disable-Timing Test Load









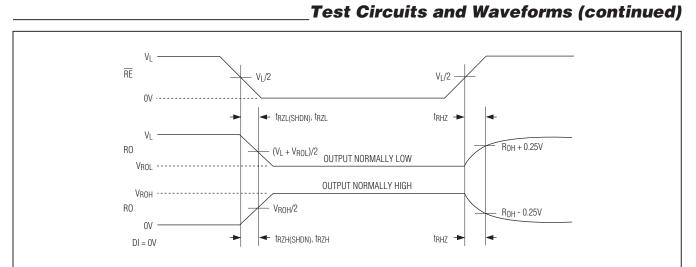


Figure 8. Receiver Enable and Disable Times

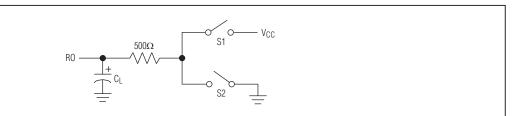


Figure 9. Receiver Enable and Disable Times

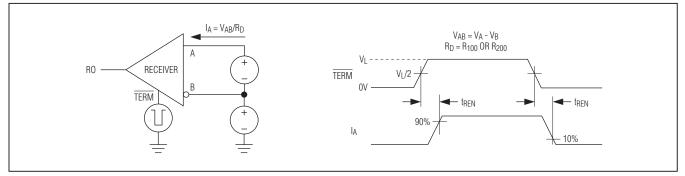
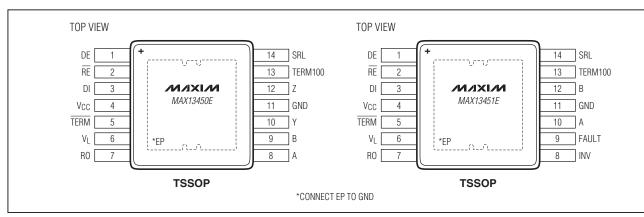


Figure 10. Termination Resistor Turn-On/-Off Times

_Pin Configurations



_Pin Description

P	IN		FUNCTION	
MAX13450E	MAX13451E	NAME	FUNCTION	
1	1	DE	Driver-Output Enable. Drive DE low to put the driver output in three-state. Drive high to enable the driver. DE is referenced to VL.	
2	2	RE	Receiver-Output Enable. Drive $\overline{\text{RE}}$ low to enable the RO. Drive $\overline{\text{RE}}$ high to disable the RO output and put the RO output in a high-impedance state. $\overline{\text{RE}}$ is referenced to VL.	
3	3	DI	Driver Input. Drive DI low to force the noninverting output low and the inverting output high. Drive DI high to force the noninverting output high and inverting output low. DI is referenced to V_L .	
4	4	V _{CC}	Power-Supply Voltage. Bypass V_{CC} to GND with a 0.1µF ceramic capacitor placed as close as possible to the device.	
5	5	TERM	Active-Low Termination Resistor Enable. Drive $\overline{\text{TERM}}$ low to enable the internal termination resistor. $\overline{\text{TERM}}$ is referenced to VL.	
6	6	VL	Logic Supply Voltage. Bypass V_L to GND with a $0.1\mu F$ ceramic capacitor placed as close as possible to the device.	
7		RO	Receiver Output. When receiver is enabled and V _A - V _B \ge -50mV, RO is high. If V _A - V _B \le -200mV, RO is low. RO is referenced to V _L .	
_	7	RO	Receiver Output. When INV is low, receiver is enabled and V _A - V _B \geq -50mV, RO is high. If V _A - V _B \leq -200mV, RO is low. When INV is high, receiver is enabled and V _A - V _B \geq -50mV, RO is low. If V _A - V _B \leq -200mV, RO is high. RO is referenced to V _L .	
8		А	Noninverting Receiver Input	
_	10	А	If INV is low, A is a noninverting receiver input and a noninverting driver output. If INV is high, A is an inverting receiver input and an inverting driver output.	
9		В	Inverting Receiver Input	
	12	В	If INV is low, B is an inverting receiver input and an inverting driver output. If INV is high, B is a noninverting receiver input and a noninverting driver output.	

Pin Description (continued)

P	IN		FUNCTION
MAX13450E	MAX13451E	NAME	FUNCTION
10		Y	Noninverting Driver Output
11	11	GND	Ground
12		Z	Inverting Driver Output
13	13	TERM100	Termination Resistor Value Selection Input. Drive TERM100 low to select a 120Ω termination and high to select a 100Ω termination. The TERM100 input is referenced to VL.
14	14	SRL	Slew-Rate Limiting-Enable Input. Drive SRL high to enable slew-rate limiting and low to disable slew-rate limiting. The SRL input is referenced to V_L .
_	8	INV	Inversion Input. Drive INV high to internally swap RO logic level with respect to A and B signals.
_	9	FAULT	Fault Flag Output. FAULT asserts high in overcurrent conditions or if A/B are forced below GND or above V_{CC} when the driver is enabled. FAULT is referenced to V_L .
		EP	Exposed Pad. Connect EP to GND. Do not use EP as the only GND connection.

Function Tables

Table 1. Termination Resistor Control(MAX13450E/MAX13451E)

TERM	DE	RE	TERMINATION RESISTOR
Low	Х	Х	Activated
High	Х	Х	Not activated

Table 2. Shutdown Control (MAX13450E/ MAX13451E)

DE	RE TERM		STATE	
Low	High	High	Shutdown	

Table 3. Function Table for Transmitter(MAX13450E)

INF	TUT	OUTPUT			
DE	DI	Y	Z		
Low	Х	High-Z	High-Z		
High	Low	Low	High		
High	High	High	Low		

Table 4. Function Table for Receiver(MAX13450E)

INPUT		OUTPUT
RE	A-B	RO
High	Х	High-Z
Low	\geq -50mV or Open	High
	≤ -200mV	Low

Table 5. INV Input Function Table forTransmitter (MAX13451E)

INPUT			OUTPUT	
DE	INV	DI	Α	В
Low	Х	Х	High-Z	High-Z
	Low	Low	Low	High
Lliab		High	High	Low
High	High	Low	High	Low
		High	Low	High

Function Tables (continued)

Table 6. INV Input Function Table forReceiver (MAX13451E)

INPUT			OUTPUT
RE	INV	A-B	RO
High	Х	Х	High-Z
Low	Low	≥ -50mV or Short or Open	High
		≤ -200mV	Low
	High	≥ -50mV or Open	Low
		≤ -200mV	High

Detailed Description

The MAX13450E is a full-duplex, RS-485/RS-422compatible transceiver and the MAX13451E is a halfduplex, RS-485/RS-422-compatible transceiver. Both devices have an internal 100 Ω /120 Ω termination resistor. The MAX13450E/MAX13451E have a VL supply voltage input to support down to a +1.8V voltage logic interface.

The MAX13450E/MAX13451E feature a 1/8-unit load receiver input impedance, allowing up to 256 transceivers on the bus. All line interface pins are protected to \pm 30kV ESD based on the HBM. These devices also include fail-safe circuitry, guaranteeing a defined logic-level receiver output when the receiver inputs are open or shorted.

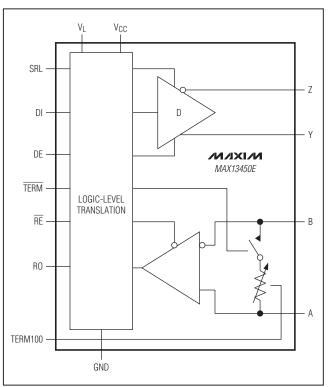
The MAX13450E/MAX13451E allow slew-rate-limited driver outputs for lower data rates below 500kbps. The SRL reduces the slew rate, which reduces EMI emissions and reflections caused by improperly terminated cables.

The MAX13451E has a FAULT output that indicates a fault condition on the driver. The MAX13451E also has an INV input that inverts the phase of A and B pins.

Termination Resistor

The MAX13450E/MAX13451E feature a selectable internal termination resistor. Drive the $\overline{\text{TERM}}$ input low to enable the internal termination resistor. Drive the $\overline{\text{TERM}}$ input high to disable the internal termination resistor.

_Functional Diagram (MAX13450E)



Drive the TERM100 input high to select the 100 $\!\Omega$ termination resistor. Drive TERM100 input low to select the 120 $\!\Omega$ termination resistor.

INV Input (MAX13451E)

The INV input of the MAX13451E reverses the polarity of the RO receiver output (see Table 5 and 6). If the INV input is high then the RO output is low under fail-safe receiver conditions. This is the opposite polarity of normal fail-safe operations.

Fault Condition (MAX13451E)

The MAX13451E also has a FAULT output to indicate a fault condition. The FAULT output is active high when there is a short circuit at the driver's output, an over/ undervoltage at the driver's outputs, or the device's temperature is higher than +150°C.

Thermal Shutdown

When the devices' temperature goes over +150°C, the termination resistor turns off, and the transmitter shuts down while the receiver stays active.

Fail Safe

The MAX13450E guarantee a logic-high receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the receiver input threshold between -50mV and -200mV. If the differential receiver input voltage (A - B) is greater than or equal to -50mV, RO is logic-high. If (A - B) is less than or equal to -200mV, RO is logic-low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0V by the termination resistor. With the receiver thresholds of the MAX13450E, this results in RO being logic-high.

The MAX13451E has the same fail-safe receiver behavior as the MAX13450E when the INV input is low. When the INV input is high, RO is low under the fail-safe condition.

ESD Protection

As with all Maxim devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the MAX13450E/MAX13451E have extra protection against static electricity. The ESD structures withstand high ESD in all states: normal operation, shutdown, and powered down. After an ESD event, the MAX13450E/MAX13451E keep working without latchup or damage.

ESD protection can be tested in various ways. The transmitter outputs and receiver inputs of the MAX13450E/ MAX13451E are characterized for protection to the following limits:

- ±30kV using the Human Body Model
- ±15kV using the Air Gap Discharge Method specified in IEC 61000-4-2
- ±7kV using the Contact Discharge Method specified in IEC 61000-4-2

ESD Test Conditions

ESD performance depends on a variety of conditions. Contact Maxim for a reliability report that documents test setup, test methodology, and test results.

Human Body Model

Figure 11a shows the Human Body Model, and Figure 11b shows the current waveform it generates when discharged into a low impedance. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a $1.5 k\Omega$ resistor.

IEC 61000-4-2

The IEC 61000-4-2 standard covers ESD testing and performance of finished equipment. However, it does not specifically refer to integrated circuits. The MAX13450E/ MAX13451E help equipment designs to meet IEC 61000-4-2, without the need for additional ESD-protection components. The major difference between tests done using the Human Body Model and IEC 61000-4-2 is higher peak current in IEC 61000-4-2 because series resistance is lower in the IEC 61000-4-2 model. Hence, the ESD withstand voltage measured to IEC 61000-4-2 is generally lower than that measured using the Human Body Model. Figure 11c shows the IEC 61000-4-2 model, and Figure 11d shows the current waveform for the IEC 61000-4-2 ESD Contact Discharge test.

Applications Information

Typical Applications

The MAX13450E transceiver is designed for full-duplex, bidirectional data communications on point-to-point or multipoint bus transmission lines (Figure 12). The MAX13451E transceiver is designed for half-duplex, bidirectional data communications on point-to-point or multipoint bus transmission lines (Figure 13).

256 Transceivers on the Bus

The standard RS-485 receiver input impedance is oneunit load, and the standard driver can drive up to 32-unit loads. The MAX13450E/MAX13451E have a 1/8-unit load receiver input impedance, allowing up to 256 transceivers to be connected in parallel on one communication line. Any combination of these devices, as well as other RS-485 transceivers with a total of 32-unit loads or fewer, can be connected to the line.

Reduced EMI and Reflections

The MAX13450E/MAX13451E feature reduced slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission up to 500kbps.

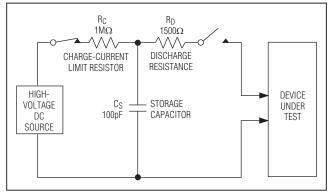


Figure 11a. Human Body ESD Test Model

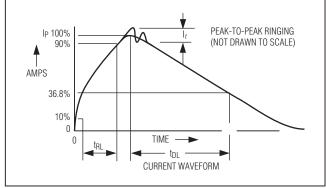


Figure 11b. Human Body Current Waveform

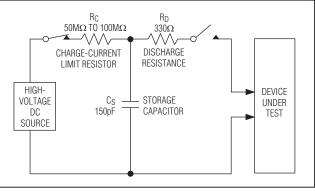


Figure 11c. IEC 61000-4-2 ESD Test Model

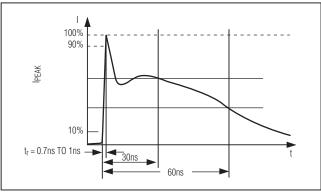
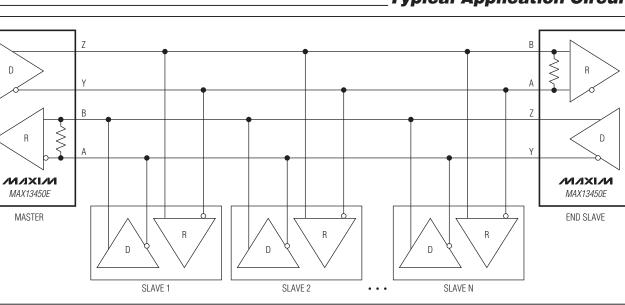


Figure 11d. IEC 61000-4-2 ESD Generator Current Waveform



Typical Application Circuits

MAX13450E/MAX13451E

Figure 12. Full-Duplex, Multidrop (MAX13450E)

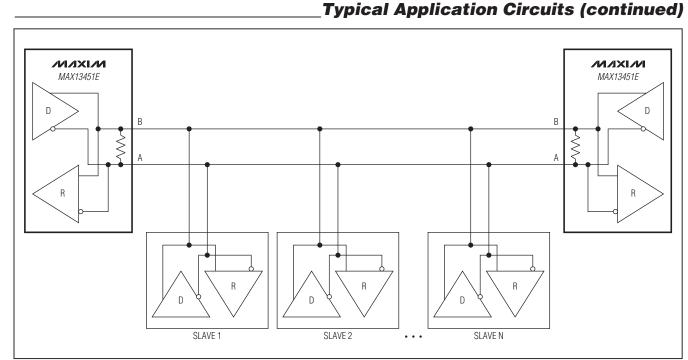


Figure 13. Half-Duplex, Multidrop, and Point-to-Point Systems (MAX13451E)

Low-Power Shutdown Mode

Drive $\overline{\text{RE}}$ high, DE low, and $\overline{\text{TERM}}$ high to enter low-power shutdown mode (see Table 2).

Chip Information

PROCESS: BiCMOS

Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE	PACKAGE	OUTLINE	LAND
TYPE	CODE	NO.	PATTERN NO.
14 TSSOP-EP	U14E+3	<u>21-0108</u>	<u>90-0119</u>

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/10	Initial release	—
1	11/10	Updated the V_L specification in the <i>Electrical Characteristics</i> and <i>Switching Characteristics</i> tables	2–5

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